

The z-Transform: Transform analysis

Quote of the Day

**Nothing in education is so astonishing
as the amount of ignorance it accumulates
in the form of inert facts.**

- Henry Adams

Difference equations

- The input output relation of discrete time system characterized by difference equation.

$$\sum_{i=0}^N a_i y(n-i) = \sum_{i=0}^M b_i x(n-i) \quad \therefore \text{Assume } a_0 = 1$$

$$y(n) = \sum_{i=0}^M b_i x(n-i) - \sum_{i=1}^N a_i y(n-i)$$

$$y(n) = \sum_{i=0}^M b_i x(n-i) - 1 \sum_{i=1}^N a_i y(n-i) \xleftarrow{z\text{-transform}} Y(z) = \sum_{i=0}^M b_i z^{-i} X(z) - \sum_{i=1}^N a_i z^{-i} Y(z)$$

$$\therefore \frac{Y(z)}{X(z)} = H(z) = \frac{\sum_{i=0}^M b_i z^{-i}}{\sum_{i=0}^N a_i z^{-i}}$$

- Where $H(z)$ is the z-transform of impulse response $h(n)$ also referred as transfer function because it represents the ratio of input and output function.

Stability and Causality

Consider a system with impulse response $h[n]$

$$y(n) = \sum_{k=-\infty}^{\infty} h(k)x(n-k)$$

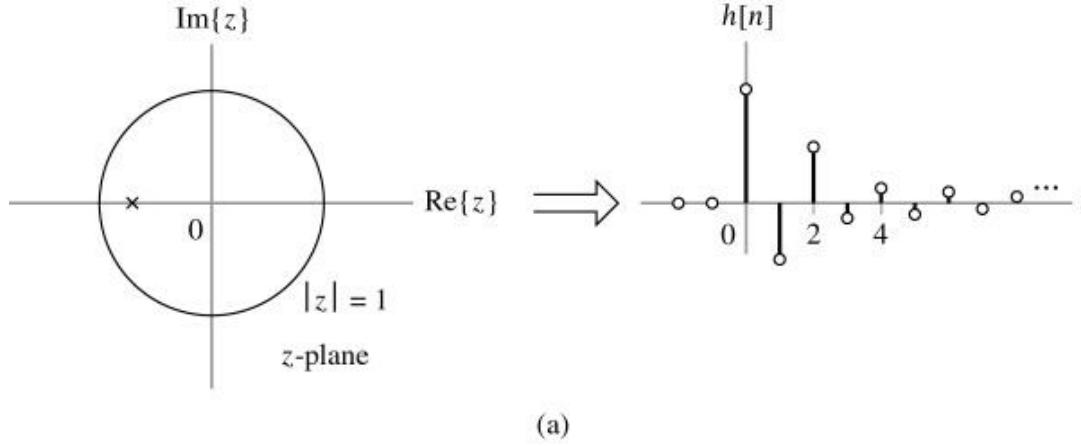
$$y(n) = \cdots h(-2)x(n+2) + h(-1)x(n+1) + h(0)x(n) + h(1)x(n-1) + h(2)x(n-2) \cdots$$

- Future instant +Present + Past instants of I/P
- For a system to be causal only present and past I/P terms should exist in the above expression.
- Therefore for system to be causal $h(n)$ should be zero for -ve instant of time.
- If system is causal then it is required that the $h(n)$ should be RHS and ROC must be $|z| > |r|$
- Now for stable system

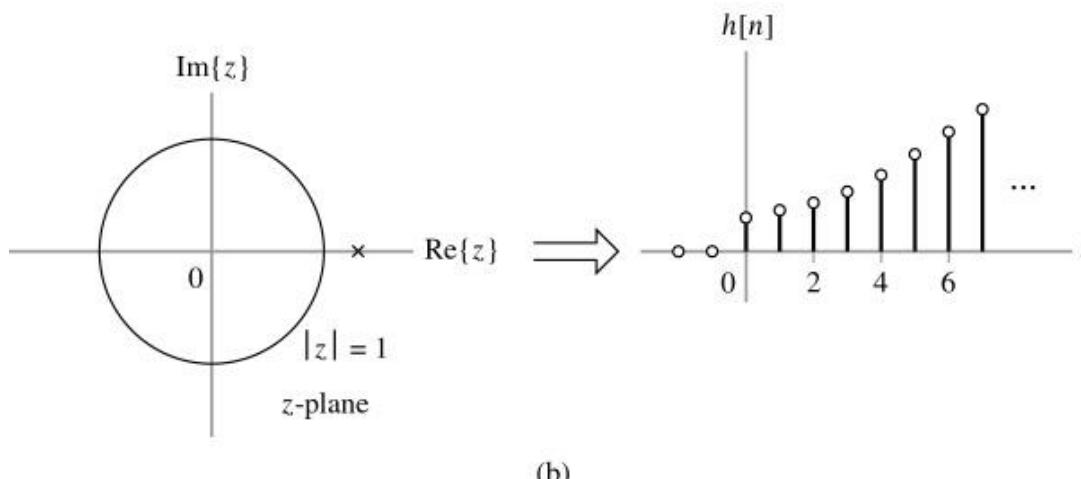
$$|y(n)| = \left| \sum_{k=-\infty}^{\infty} h(k)x(n-k) \right| = \sum_{k=-\infty}^{\infty} |h(k)| |x(n-k)| < \infty$$
- If $|x(n-k)|$ is Mx then for system to be stable it is required that $\sum_{k=-\infty}^{\infty} |h(k)| < \infty$. i.e if system is stable then it is required that the $h(n)$ should be absolutely summable.

Figure 7.14 (p. 583)

The relationship between the location of a pole and the impulse response characteristics for a causal system. (a) A pole inside the unit circle contributes an exponentially decaying term to the impulse response. (b) A pole outside the unit circle contributes an exponentially increasing term to the impulse response.



(a)



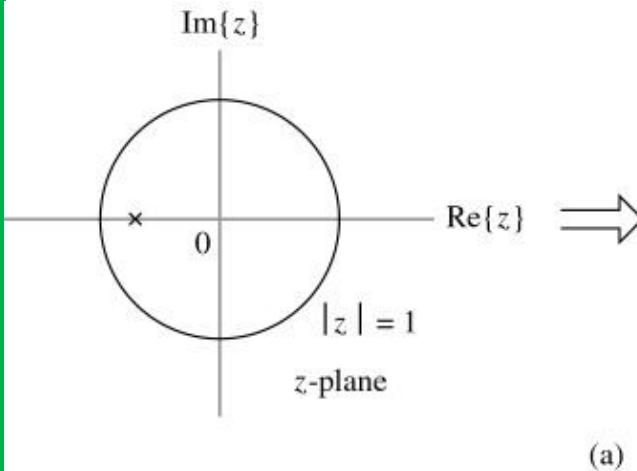
(b)

- If $h(n)$ is R.H.S & $|r| < 1$ then
Causal, stable system

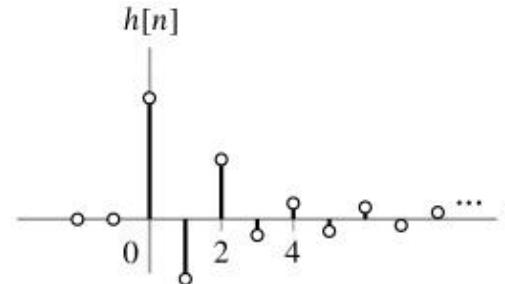
- If $h(n)$ is R.H.S & $|r| > 1$
Then system may be Causal but cannot be stable

Figure 7.15 (p. 583)

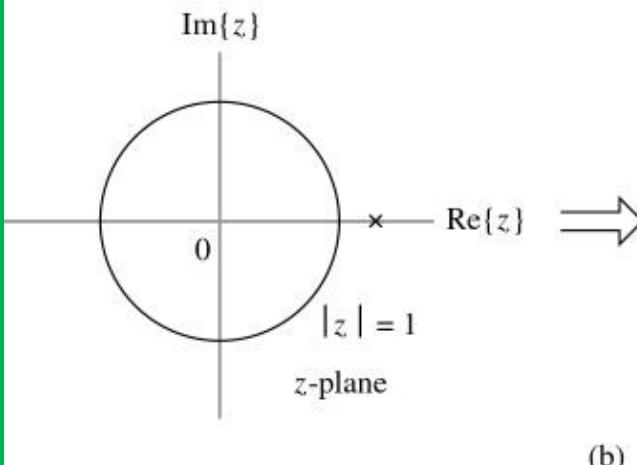
The relationship between the location of a pole and the impulse response characteristics for a stable system. (a) A pole inside the unit circle contributes a right-sided term to the impulse response. (b) A pole outside the unit circle contributes a left-sided term to the impulse response.



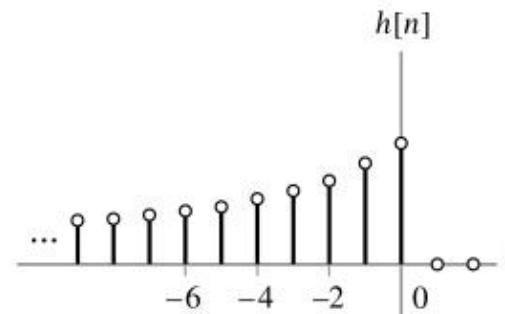
(a)



- If $h(n)$ is R.H.S & $|r| < 1$ then **Causal, stable system**



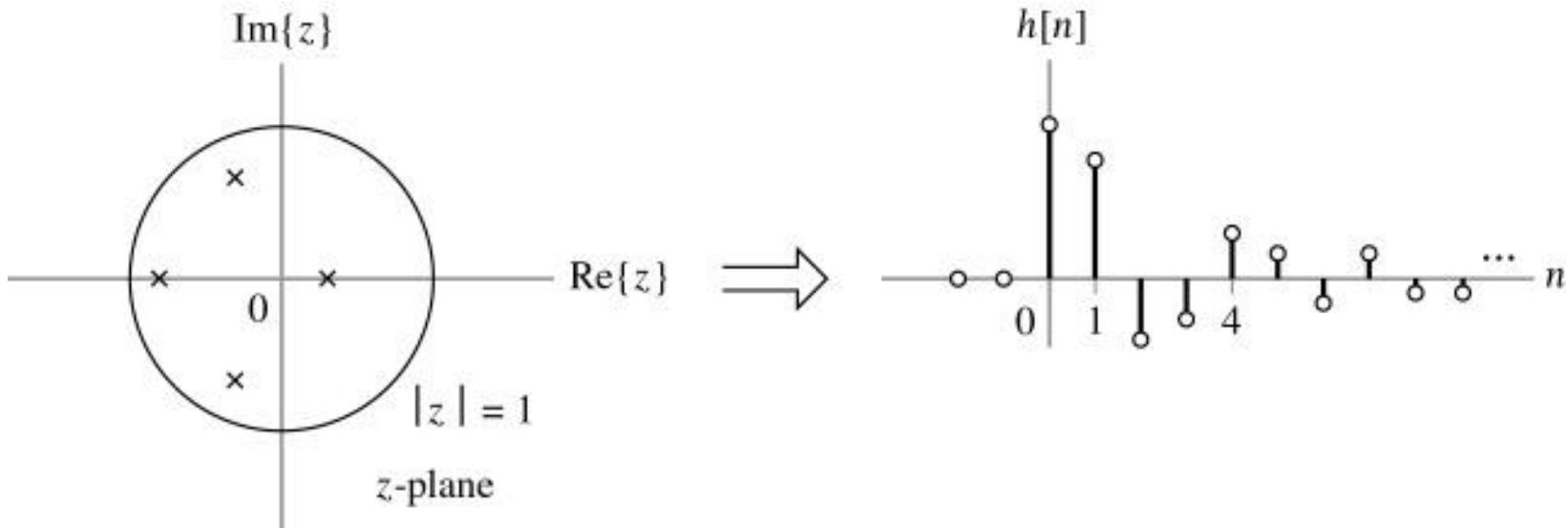
(b)



- If $h(n)$ is L.H.S & $|r| > 1$ then **Non causal, stable system**

Figure 7.16 (p. 584)

A system that is both stable and causal must have all its poles inside the unit circle in the z-plane, as illustrated here.



In any other case except described until system can not be both stable and causal.(If $h(n)$ is LHS and $|r|<1$)

Ex:1.A causal system has input $x(n)$ and output $y(n)$, find impulse response of the system,

$$x[n] = \delta[n] + \frac{1}{4}\delta[n-1] - \frac{1}{8}\delta[n-2] \quad y[n] = \delta[n] - \frac{3}{4}\delta[n-1]$$

impulse response: $H(z) = \frac{Y(z)}{X(z)}$ $H(z) \xleftarrow{IZT} h(n)$

Obtain $Y(z)$ and $X(z)$ then take ratio of them to find $H(z)$

$$\therefore X(z) = 1 + \frac{1}{4}z^{-1} - \frac{1}{8}z^{-2} \quad \therefore Y(z) = 1 - \frac{3}{4}z^{-1}$$

$$H(z) = \frac{Y(z)}{X(z)} = \frac{1 - \frac{3}{4}z^{-1}}{1 + \frac{1}{4}z^{-1} - \frac{1}{8}z^{-2}} = \frac{z^2 - \frac{3}{4}z}{z^2 + \frac{1}{4}z - \frac{1}{8}} = \frac{z^2 - \frac{3}{4}z}{\left(z - \frac{1}{4}\right)\left(z + \frac{1}{2}\right)}$$

$$\therefore \frac{H(z)}{z} = \frac{z - \frac{3}{4}}{\left(z - \frac{1}{4}\right)\left(z + \frac{1}{2}\right)} = \frac{A_1}{\left(z - \frac{1}{4}\right)} + \frac{A_2}{\left(z + \frac{1}{2}\right)}$$

Ex:1, A causal system has input $x(n)$ and output $y(n)$, find impulse response of the system,

$$\therefore A_1 = \frac{\left(z - \frac{1}{4} \right) \left(z - \frac{3}{4} \right)}{\left(z - \frac{1}{4} \right) \left(z + \frac{1}{2} \right)} \Big|_{z=\frac{1}{4}} = \frac{\frac{1}{4} - \frac{3}{4}}{\frac{1}{4} + \frac{1}{2}} = \frac{-2}{3} \quad \therefore A_2 = \frac{\left(z + \frac{1}{2} \right) \left(z - \frac{3}{4} \right)}{\left(z - \frac{1}{4} \right) \left(z + \frac{1}{2} \right)} \Big|_{z=-\frac{1}{2}} = \frac{-\frac{1}{2} - \frac{3}{4}}{-\frac{1}{2} - \frac{1}{4}} = \frac{5}{3}$$

$$\therefore H(z) = \frac{-z^{\frac{2}{3}}}{\left(z - \frac{1}{4} \right)} + \frac{z^{\frac{5}{3}}}{\left(z + \frac{1}{2} \right)}$$

Impulse response for causal system should be RHS

$$\therefore h(n) = -\frac{1}{3} \left(\frac{1}{4} \right)^n u(n) + \frac{1}{3} \left(-\frac{1}{2} \right)^n u(n)$$

$$\therefore h(n) = \frac{1}{3} \left[5 \left(-\frac{1}{2} \right)^n - 2 \left(\frac{1}{4} \right)^n \right] u(n)$$

Ex:2, A DT LTI system is given by

$$\therefore H(z) = \frac{3 - 4z^{-1}}{\left(1 - \frac{1}{2}z^{-1} + \frac{3}{2}z^{-2}\right)}$$

Specify the ROC of $H(z)$ and determine impulse response for the following conditions

- Stable system
- Causal system
- Non causal system

$$\therefore H(z) = \frac{3z^2 - 4z}{\left(z^2 - \frac{1}{2}z + \frac{3}{2}\right)} \quad \therefore \frac{H(z)}{z} = \frac{3z - 4}{(z - 3)(z - \frac{1}{2})} = \frac{A_1}{(z - 3)} + \frac{A_2}{(z - \frac{1}{2})}$$

$$\therefore A_1 = \left. \frac{3z - 4}{(z - \frac{1}{2})} \right|_{z=3} = \frac{9 - 4}{3 - \frac{1}{2}} = 2 \quad \therefore A_2 = \left. \frac{3z - 4}{(z - 3)} \right|_{z=\frac{1}{2}} = \frac{\frac{3}{2} - 4}{\frac{1}{2} - 3} = 1$$

$$\therefore H(z) = \frac{2z}{(z - 3)} + \frac{z}{(z - \frac{1}{2})}$$

- Stable system: pole at 3 corresponds to LHS and pole at $\frac{1}{2}$ corresponds to RHS ROC will be $|1/2| < |z| < |3|$

$$\therefore h(n) = -2(3)^n u(-n-1) + \left(\frac{1}{2}\right)^n u(n)$$

Ex:2, contd..

- Causal system: pole at 3 and $\frac{1}{2}$ both corresponds to RHS ROC will be $|z|>|3|$

$$\therefore h(n) = 2(3)^n u(n) + \left(\frac{1}{2}\right)^n u(n)$$

- Non Causal system: pole at 3 and $\frac{1}{2}$ both corresponds to LHS ROC will be $|z|<|\frac{1}{2}|$

$$\therefore h(n) = -2(3)^n u(-n-1) - \left(\frac{1}{2}\right)^n u(-n-1)$$

Ex:3, Step response of a LTI system is found to be $y(n)=2(1/3)^n u[n]$. Find out impulse response of the system.

$$H(z) = \frac{Y(z)}{X(z)} \quad X(z) = \frac{z}{z-1} \quad y(n) = 2\left(\frac{1}{3}\right)^n u(n) \xrightarrow{ZT} Y(z) = 2 \frac{z}{z - \frac{1}{3}}$$

$$\therefore H(z) = \frac{\cancel{z}}{\cancel{z-1}} \frac{2(z-1)}{z - \frac{1}{3}} = \frac{2z}{z - \frac{1}{3}} - \frac{2}{z - \frac{1}{3}} = \frac{2z}{z - \frac{1}{3}} - z^{-1} \frac{2z}{z - \frac{1}{3}}$$

$$\therefore h(n) = 2 \left[\left(\frac{1}{3}\right)^n u(n) - \left(\frac{1}{3}\right)^{n-1} u(n-1) \right]$$

Ex:4, Find the impulse response if a stable and causal system described by difference equation

$$y(n) + \frac{1}{4}y(n-1) - \frac{1}{8}y(n-2) = 2x(n) + \left(\frac{5}{4}\right)x(n-1)$$

→ Taking the ZT of the given equation.

$$Y(z) + \frac{1}{4}z^{-1}Y(z) - \frac{1}{8}z^{-2}Y(z) = 2X(z) + \left(\frac{5}{4}\right)z^{-1}X(z)$$

$$Y(z)\left(1 + \frac{1}{4}z^{-1} - \frac{1}{8}z^{-2}\right) = \left(2 + \left(\frac{5}{4}\right)z^{-1}\right)X(z)$$

$$\therefore H(z) = \frac{Y(z)}{X(z)} = \frac{\left(2 + \left(\frac{5}{4}\right)z^{-1}\right)}{\left(1 + \frac{1}{4}z^{-1} - \frac{1}{8}z^{-2}\right)} = \frac{2z^2 + \frac{5}{4}z}{z^2 + \frac{1}{4}z - \frac{1}{8}}$$

$$\therefore \frac{H(z)}{z} = \frac{2z + \frac{5}{4}}{z^2 + \frac{1}{4}z - \frac{1}{8}} = \frac{2z + \frac{5}{4}}{(z + \frac{1}{2})(z - \frac{1}{4})} = \frac{A_1}{(z + \frac{1}{2})} + \frac{A_2}{(z - \frac{1}{4})}$$

$$A_1 = -\frac{1}{3} \quad \text{and} \quad A_2 = \frac{7}{3}$$

$$\therefore H(z) = -\frac{\frac{1}{3}z}{(z + \frac{1}{2})} + \frac{\frac{7}{3}z}{(z - \frac{1}{4})}$$

$$\therefore h(n) = -\frac{1}{3}\left(\frac{-1}{2}\right)^n u(n) + \frac{7}{3}\left(\frac{1}{4}\right)^n u(n)$$

Ex:5, Find the impulse function $H(z)$ and unit sample response $h(n)$ of the system described by difference equation. Also find stability of system.(July15,

$$y(n) - 2y(n-1) + 2y(n-2) = x(n) + \left(\frac{1}{2}\right)x(n-1)$$

→ Taking the ZT of the given equation.

$$Y(z) - 2z^{-1}Y(z) + 2z^{-2}Y(z) = X(z) + \left(\frac{1}{2}\right)z^{-1}X(z)$$

$$Y(z)\left(1 - 2z^{-1} + 2z^{-2}\right) = \left(1 + \left(\frac{1}{2}\right)z^{-1}\right)X(z)$$

$$\therefore H(z) = \frac{Y(z)}{X(z)} = \frac{\left(1 + \left(\frac{1}{2}\right)z^{-1}\right)}{\left(1 - 2z^{-1} + 2z^{-2}\right)} = \frac{z^2 + \frac{1}{2}z}{z^2 - 2z + 2}$$

$$\therefore \frac{H(z)}{z} = \frac{z + \frac{1}{2}}{(z - 1 + j)(z - 1 - j)} = \frac{A_1}{(z - 1 + j)} + \frac{A_2}{(z - 1 - j)}$$

$$A_1 = \frac{1}{2} + \frac{3}{4}j \quad \text{and} \quad A_2 = \frac{1}{2} - \frac{3}{4}j \quad \therefore H(z) = -\frac{\left(\frac{1}{2} + \frac{3}{4}j\right)z}{\left(z - 1.414e^{j3\pi/4}\right)} + \frac{\left(\frac{1}{2} - \frac{3}{4}j\right)z}{\left(z - 1.414e^{-j3\pi/4}\right)}$$

The roots are not lying inside the unit circle hence not a stable system.

$$\text{and } h(n) = 0.9014e^{j56.31} \left(1.414e^{j3\pi/4}\right)^n u(n) + 0.9014e^{-j56.31} \left(1.414e^{-j3\pi/4}\right)^n u(n)$$

$$\therefore h(n) = 0.9014(1.414)^n \left(e^{j56.31} e^{\frac{j3\pi n}{4}} + e^{-j56.31} e^{\frac{-j3\pi n}{4}} \right) u(n)$$

$$\therefore h(n) = 0.9014(1.414)^n \left(e^{\frac{j3\pi n}{4} + j56.31} + e^{\frac{-j3\pi n}{4} - j56.31} \right) u(n)$$

$$\therefore h(n) = 0.9014(1.414)^n \left(e^{j\left(\frac{3\pi n}{4} + 56.31\right)} + e^{-j\left(\frac{3\pi n}{4} + 56.31\right)} \right) u(n) = 1.8028(1.414)^n \left(\cos \frac{\pi n}{4} + 56.31 \right) u(n)$$

Ex:6, Find impulse response of the causal system

$$y(n) - y(n-1) = x(n) + x(n-1)$$

→ Taking the ZT of the given equation.

$$Y(z) - z^{-1}Y(z) = X(z) + z^{-1}X(z) \Rightarrow Y(z)(1 - z^{-1}) = (1 + z^{-1})X(z)$$

$$\therefore H(z) = \frac{Y(z)}{X(z)} = \frac{(1 + z^{-1})}{(1 - z^{-1})} = \frac{z + 1}{z - 1}$$

$$\therefore H(z) = \frac{Y(z)}{X(z)} = \frac{z}{z-1} + \frac{1}{z-1} = \frac{z}{z-1} + z^{-1} \frac{z}{z-1}$$

$$\therefore h(n) = u(n) + u(n-1)$$

Ex:7, Find the impulse response if a stable and causal system described by difference equation also find the magnitude response at zero frequency.

$$y(n) = \frac{5}{6} y(n-1) - \frac{1}{6} y(n-2) + x(n) - 2x(n-1)$$

→ Taking the ZT of the given equation.

$$Y(z) - \frac{5}{6} z^{-1} Y(z) + \frac{1}{6} z^{-2} Y(z) = X(z) - 2z^{-1} X(z)$$

$$Y(z) \left(1 - \frac{5}{6} z^{-1} + \frac{1}{6} z^{-2}\right) = (1 - 2z^{-1}) X(z)$$

$$\therefore H(z) = \frac{Y(z)}{X(z)} = \frac{(1 - 2z^{-1})}{\left(1 - \frac{5}{6} z^{-1} + \frac{1}{6} z^{-2}\right)} = \frac{z^2 - 2z}{z^2 - \frac{5}{6} z + \frac{1}{6}}$$

$$\therefore \frac{H(z)}{z} = \frac{z - 2}{\left(z - \frac{1}{2}\right)\left(z - \frac{1}{3}\right)} = \frac{A_1}{\left(z - \frac{1}{2}\right)} + \frac{A_2}{\left(z - \frac{1}{3}\right)}$$

$$A_1 = -9 \quad \text{and} \quad A_2 = 10 \quad \therefore H(z) = -\frac{9z}{\left(z - \frac{1}{2}\right)} + \frac{10z}{\left(z - \frac{1}{3}\right)}$$

$$\therefore h(n) = -9\left(\frac{1}{2}\right)^n u(n) + 10\left(\frac{1}{3}\right)^n u(n)$$

To find the frequency response substitute $z=e^{j\Omega}$ in $H(z)$

$$\therefore H(z) = \frac{z^2 - 2z}{z^2 - \frac{5}{6}z + \frac{1}{6}} = \frac{z^2 - 2z}{(z - \frac{1}{2})(z - \frac{1}{3})} \rightarrow \therefore H(e^{j\Omega}) = \frac{e^{j2\Omega} - 2e^{j\Omega}}{(e^{j\Omega} - \frac{1}{2})(e^{j\Omega} - \frac{1}{3})}$$

$$\therefore |H(e^{j\Omega})| = \frac{|e^{j2\Omega} - 2e^{j\Omega}|}{|(e^{j\Omega} - \frac{1}{2}) \cdot (e^{j\Omega} - \frac{1}{3})|} = \left| \frac{|e^{j2\Omega} - 2e^{j\Omega}|}{|(e^{j\Omega} - \frac{1}{2}) \cdot (e^{j\Omega} - \frac{1}{3})|} \right|_{\Omega=0}$$

$$\therefore |H(e^{j\Omega})|_{\Omega=0} = \frac{|1 - 2|}{|(1 - \frac{1}{2}) \cdot (1 - \frac{1}{3})|} = 3$$

- Observe the magnitude response of system is magnitude of numerator polynomial by the magnitude of denominator polynomial of $H(e^{j\Omega})$.
- Similarly the phase response of system is phase of numerator polynomial minus the phase of denominator polynomial of $H(e^{j\Omega})$.

Ex:8, Determine the impulse response system described by difference equation.

$$y(n) - 2y(n-1) + y(n-2) = x(n) + 3x(n-3)$$

→ Taking the ZT of the given equation.

$$Y(z) - 2z^{-1}Y(z) + z^{-2}Y(z) = X(z) - 3z^{-3}X(z)$$

$$Y(z)(1 - 2z^{-1} + z^{-2}) = (1 - 3z^{-3})X(z)$$

$$\therefore H(z) = \frac{Y(z)}{X(z)} = \frac{(1 - 3z^{-3})}{(1 - 2z^{-1} + z^{-2})} = \frac{z^2 - 3z^{-1}}{(z^2 - 2z + 1)} = \frac{z^2 - 3z^{-1}}{(z - 1)^2}$$

$$\therefore H(z) = \frac{z^2}{(z - 1)^2} - \frac{3z^{-1}}{(z - 1)^2} = z \frac{z}{(z - 1)^2} - 3z^{-2} \frac{z}{(z - 1)^2}$$

$$\therefore h(n) = (n+1)u(n+1) - 3(n-2)u(n-2)$$

Find inverse z- transform of

$$X(z) = \frac{5z(z-1)}{(z^2 - 1.6z + 0.8)} = \frac{5z(z-1)}{(z-0.8-j0.4)(z-0.8+j0.4)}$$

$$\therefore \frac{X(z)}{z} = \frac{5(z-1)}{(z-0.8-j0.4)(z-0.8+j0.4)} = \frac{A_1}{(z-0.8-j0.4)} + \frac{A_2}{(z-0.8+j0.4)}$$

$$A_1 = 2.5 + 1.25j \quad \text{and} \quad A_2 = 2.5 - 1.25j$$

$$A_1 = 2.8e^{j26.56} \quad \text{and} \quad A_2 = 2.8e^{-j26.56}$$

$$\therefore X(z) = \frac{2.8e^{j26.56}z}{(z+0.8-j0.4)} + \frac{2.8e^{-j26.56}z}{(z+0.8+j0.4)}$$

$$X(z) = \frac{2.8e^{j26.56}z}{(z+0.89e^{j26.56})} + \frac{2.8e^{-j26.56}z}{(z+0.89e^{-j26.56})}$$

$$\therefore x(n) = 2.8e^{j56.26} \left(0.89e^{j26.56}\right)^n u(n) + 2.8e^{-j56.26} \left(0.89e^{-j26.56}\right)^n u(n)$$

$$\therefore x(n) = 2.8(0.89)^n \left(e^{j56.26(n+1)} + e^{-j56.26(n+1)}\right) = 2.8(0.89)^n \cos(56.26(n+1))$$

Find inverse z- transform of

$$X(z) = \frac{9}{(z+2)(z-0.5)^2}$$

$$\therefore \frac{X(z)}{z} = \frac{9}{z(z+2)(z-0.5)^2} = \frac{A_1}{z} + \frac{A_2}{(z+2)} + \frac{C_1}{(z-0.5)} + \frac{C_2}{(z-0.5)^2}$$

$$A_1 = \frac{9}{(2)(-0.5)^2} = 4.5 \quad \therefore A_2 = \frac{9}{-2(-2-0.5)^2} = -0.72 \quad \therefore C_1 = \frac{9}{0.5(0.5+2)} = 7.2$$

$$\text{and } C_2 = \left. \frac{d}{dz} \frac{9}{(z^2 + 2z)} \right|_{z=0.5} = \left. \frac{-9(2z+2)}{(z^2 + 2z)^2} \right|_{z=0.5} = \frac{-9(2 \times 0.5 + 2)}{(0.5^2 + 2 \times 0.5)^2} = -5.355$$

$$\therefore X(z) = 4.5 - 0.72 \frac{z}{(z+2)} + 7.2 \frac{z}{(z-0.5)} - 5.355 \frac{z}{(z-0.5)^2}$$

$$\therefore x(n) = 4.5\delta(n) - 0.72(2)^n u(n) + 7.2(0.5)^n u(n) - 5.355n(0.5)^{n-1} u(n)$$

Some examples for exercise from QP

$$1) y(n) = \frac{5}{6}y(n-1) - \frac{1}{6}y(n-2) + x(n) - 2x(n-1)$$

Determine

- i) System function $H(z)$ and magnitude response at zero frequency.
- ii) Impulse response of the system.
- iii) Output $y(n)$ for $x(n) = \delta(n) - \frac{1}{3}\delta(n-1)$

2) An LT1 system is described by the equation

$$y(n) = x(n) + 0.8x(n-1) + 0.8x(n-2) - 0.49y(n-2)$$

3) Determine the transfer function $H(z)$ of the system and also sketch the poles and zeros.
 Find the difference – equation description for a system with transform function :

$$H(z) = \frac{y(z)}{x(z)} = \frac{5z+2}{z^2+3z+2}$$

4) A discrete LTI system is characterized by the difference equation,
 $y(n) = y(n-1) + y(n-2) + x(n-1)$

Find the system function $H(z)$ and indicate the ROC if the system, i) Stable ii) Causal.
 Also determine the unit sample response of the stable system. (10 Marks)

Examples for exercise from QP contd.

- a. A system has impulse response $h(n) = \left(\frac{1}{2}\right)^n u(n)$, determine the input to the system if the output is given by,

$$y(n) = \frac{1}{3}u(n) + \frac{2}{3}\left(-\frac{1}{2}\right)^n u(n). \quad (08 \text{ Marks})$$

- b. A systems has impulse response $h(n) (\gamma_3)^n u(n)$. Determine the transfer function. Also determine the input to the system if the output is given by:

$$y(n) = \frac{1}{2}u(n) + \frac{1}{4}\left(-\frac{1}{3}\right)^n u(n). \quad (05 \text{ Marks})$$

- 8 a. A system has the transfer function,

$$H(z) = \frac{2}{1 - 0.9e^{j\frac{\pi}{4}}z^{-1}} + \frac{2}{1 - 0.9e^{j\frac{3\pi}{4}}z^{-1}} + \frac{3}{1 + 2z^{-1}}.$$

Find the impulse response assuming the system is (i) stable and (ii) causal. (10 Marks)

- b. A system is described by the difference equation :

$$y(n) - y(n-1) + \frac{1}{4}y(n-2) = x(n) + \frac{1}{4}x(n-1) - \frac{1}{8}x(n-2).$$

Find the transfer function of the system. (05 Marks)